

Data sheet for SINAMICS G120C

Article No.: 6SL3210-1KE31-1UF1

Client order no. : Order no. : Offer no. : Remarks :





Figure similar

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 %	b -20 %
Line frequency	47 63 Hz	
Rated current (LO)	96.00 A	
Rated current (HO)	85.00 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC 1)
Rated power (LO)	55.00 kW	60.00 hp
Rated power (HO)	45.00 kW	50.00 hp
Rated current (LO)	103.00 A	
Rated current (HO)	83.00 A	
Rated current (IN)	103.00 A	
Max. output current	165.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload	capability
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Low Overload (LO)

 $150\,\%$ base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

 $200\,\%$ base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications	
Power factor λ	0.90 0.95
Offset factor $\cos\phi$	0.99
Efficiency η	0.98
Sound pressure level (1m)	71 dB
Power loss	1,570.0 W
Filter class (integrated)	Unfiltered
Communication	

Communication PROFINET, EtherNet/IP

Inputs / outputs		
Standard digital inputs		
Number	6	
Switching level: 0→1	11 V	
Switching level: 1→0	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number	1	
Digital outputs		
Number as relay changeover contact	1	
Output (resistive load)	DC 30 V, 0.5 A	
Number as transistor	1	
Output (resistive load)	DC 30 V, 0.5 A	
Analog / digital inputs		
Number	1 (Differential input)	
Resolution	10 bit	
Switching threshold as digital input		
0→1	4 V	
1→0	1.6 V	
Analog outputs		
Number	1 (Non-isolated output)	
PTC/ KTY interface		

TC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5\,^{\circ}\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



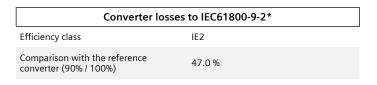
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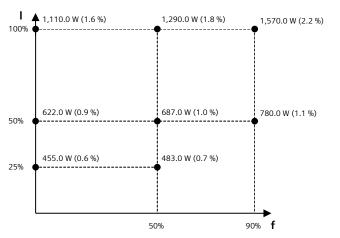
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Ambie	ent conditions
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.083 m ³ /s (2.931 ft ³ /s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-20 40 °C (-4 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)
Relative humidity	
Max. operation	95 % RH, condensation not permitted
Co	onnections
Signal cable	
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)
Line side	
Version	screw-type terminal
Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG -1)
Motor end	
Version	Screw-type terminals
Conductor cross-section	25.00 70.00 mm ² (AWG 4 AWG -1)
DC link (for braking resistor)	
Version	Screw-type terminals
Conductor cross-section	25.00 70.00 mm ² (AWG 4 AWG -1)
Line length, max.	10 m (32.81 ft)
PE connection	Screw-type terminals
Max. motor cable length	
Shielded	200 m (656.17 ft)
Unshielded	300 m (984.25 ft)

Mechanical data		
Degree of protection	IP20 / UL open type	
Frame size	FSE	
Net weight	26.50 kg (58.42 lb)	
Dimensions		
Width	275 mm (10.83 in)	
Height	551 mm (21.69 in)	
Depth	237 mm (9.33 in)	

Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

^{*}converted values

 $^{^{1)}}$ The output current and HP ratings are valid for the voltage range 440V-480V